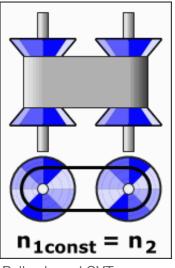
## WikipediA

# **Continuously variable transmission**

A **continuously variable transmission** (**CVT**) is an <u>automatic</u> transmission that can change seamlessly through a continuous range of gear ratios. This contrasts with other transmissions that provide a limited number of gear ratios in fixed steps. The flexibility of a CVT with suitable control may allow the engine to operate at a constant RPM while the vehicle moves at varying speeds.

CVTs are used in automobiles, tractors, motor scooters, snowmobiles and earthmoving equipment.

The most common type of CVT uses two pulleys connected by a belt or chain, however several other designs have also been used at times.



Pulley-based CVT

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### **Pulley-based**

The most common type of CVT uses a <u>V-belt</u> which runs between two variable diameter pulleys.<sup>[1]</sup> The pulleys consist of two cone-shaped halves which move together and apart. The V-belt runs between these two halves, so the effective diameter of the pulley is dependent on the distance between the two halves of the pulley. The V-shaped cross section of the belt causes it to ride higher on one pulley and lower on the other, therefore the gear ratio is adjusted by moving the two sheaves of one pulley closer together and the two sheaves of the other pulley farther apart.<sup>[2]</sup>

As the distance between the pulleys and the length of the belt does not change, both pulleys must be adjusted (one bigger, the other smaller) simultaneously in order to maintain the proper amount of tension on the belt. Simple CVTs combining a centrifugal drive pulley with a spring loaded driven pulley often use belt tension to effect the conforming adjustments in the driven pulley.<sup>[2]</sup> The V-belt needs to be very stiff in the pulley's axial direction in order to make only short radial movements while sliding in and out of the pulleys.

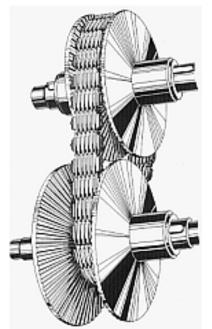
The pulley-radial thickness of the belt is a compromise between maximum gear ratio and torque. Steel reinforced v-belts are sufficient for low-mass low-torque applications like utility vehicles and snowmobiles but higher mass and torque applications such as automobiles require a chain. Each element of the chain must have conical sides that fit the pulley when the belt is running on the outermost radius. As the chain moves into the pulleys the contact area gets smaller. As the contact area is proportional to the number of elements, chain belts require many very small elements.

A belt-driven design offers approximately 88% efficiency,<sup>[3]</sup> which, while lower than that of a manual transmission, can be offset by enabling the engine to run at its most efficient RPM regardless of the vehicle's speed. When power is more important than economy, the ratio of the CVT can be changed to allow the engine to turn at the RPM at which it produces greatest power.<sup>[4]</sup>

In a chain-based CVT a film of lubricant is applied to the pulleys. It needs to be thick enough so that the pulley and the chain never touch and it must be thin in order not to waste power when each element



Belt-driven CVT for a motor scooter



Chain-driven CVT used in cars and motor scooters



dives into the lubrication film. Additionally, the chain elements stabilize about 12 steel bands. Each band is thin enough so that it bends easily. If bending, it has a perfect conical surface on its side. In the stack of bands each band corresponds to a slightly different drive ratio, and thus they slide over each other and need oil between them. Also the outer bands slide through the stabilizing chain, while the center band can be used as the chain linkage.

CVT in a <u>Claas Mercator</u> combine harvester. The pulley's diameter can be changed by pushing the two cone-shaped discs either towards or away from each other

Some CVTs transfer power to the output pulley via tension in the belt (a "pulling" force), while others use *link element* compression where the input pulley "pushes" the belt which in turn pushes the output pulley. [5][6][7]

### Toroidal

Toroidal CVTs, as used on the 1999 <u>Nissan Cedric (Y34)</u>,<sup>[8][9]</sup> consist of a series of discs and rollers. The discs can be pictured as two almost conical parts, point to point, with the sides dished such that the two parts could fill the central hole of a torus. One disc is the input, and the other is the output. Between the discs are rollers which vary the ratio and which transfer power from one side to the other. When the roller's axis is perpendicular to the axis of the discs, the effective diameter is the same for the input discs and the output discs, resulting in a 1:1 drive ratio. For other ratios, the rollers are moved along the axis of the discs, resulting in the rollers being in contact with the discs at a point which has a larger or smaller diameter, giving a drive ratio of something other than 1:1.<sup>[10]</sup>



Toroidal CVT used in the <u>Nissan</u> Cedric (Y34)

An advantage of a toroidal CVT is the ability to withstand higher torque loads than a pulley-based CVT.<sup>[11]</sup> In some toroidal systems, the direction of thrust can be reversed within the CVT, removing the need for an external device to provide a reverse gear.<sup>[12]</sup>

CVTCORP is another company that developed a high powered CVT in 2001 that is now used primarily for the construction and agricultural industries. Their traction drive CVT functions by transferring torque and power from the input (end) flanges to the output (center) flange through 6 actuated rollers. No metal to metal contact occurs as the specially formulated traction oil used in the transmission is trapped at each contact point between rolling element surfaces. The pressure at contact points induces a phase change in the oil which then momentarily becomes visco-elastic, allowing torque to be transferred without slippage. [13]

### Ratcheting

A ratcheting CVT uses a series of one-way clutches or <u>ratchets</u> that rectify and sum only "forward" motion. The on-off characteristics of a typical ratchet means that many of these designs are not continuous in operation (i.e. technically not a CVT), however in practice there are many similarities in operation and a ratcheting CVT is able to produce a zero output speed from any given input speed (as per an Infinitely Variable Transmission). The drive ratio is adjusted by changing linkage geometry within the oscillating elements, so that the summed maximum linkage speed is adjusted, even when the average linkage speed remains constant.

Ratcheting CVTs can transfer substantial torque, because their static friction actually increases relative to torque throughput, so slippage is impossible in properly designed systems. Efficiency is generally high, because most of the dynamic friction is caused by very slight transitional clutch speed changes. The drawback to ratcheting CVTs is vibration caused by the successive transition in speed required to accelerate the element, which must supplant the previously operating and decelerating, power transmitting element.

The design principle dates back to before the 1930s, with the original design intended to convert rotary motion to oscillating motion and back to rotary motion using roller clutches.<sup>[14]</sup> This design remains in production as of 2017, for use with low speed electric motors.<sup>[15]</sup> A prototyped as a bicycle transmission was patented in 1994.<sup>[16]</sup> The operating principle for a ratcheting CVT design using a scotch yoke mechanism to convert rotary motion to oscillating motion and non-circular gears, to achieve uniform input to output ratio, was patented in 2014. <sup>[17]</sup>

### Hydrostatic

Hydrostatic CVTs use a variable displacement pump and a hydraulic motor, therefore the transmission converts hydraulic pressure to rotation of the output shaft. The advantages of hydrostatic CVTs are:

- ability to transmit more torque
- can be mounted directly to the wheel hub, allowing a more flexible suspension system and reducing drivetrain losses
- all forward and reverse speeds can be accessed using a single lever.



Hydrostatic CVT used in a Honda DN-01 motorcycle

However, the design can be sensitive to contamination and expensive to produce. They are not suited to transmitting high torque for extended durations, since the hydraulic fluid can overheat in these circumstances.

Uses of hydrostatic CVTs include forage harvesters, combine harvesters, small wheeled/tracked/skidsteer loaders, crawler tractors, and road rollers. One agricultural example, produced by AGCO Corporation, splits power between hydrostatic and mechanical transfer to the output shaft via a planetary gear in the forward direction of travel (in reverse the power transfer is fully hydrostatic).<sup>[18]</sup> A variant called the *Integrated Hydrostatic Transaxle* (IHT) uses a single housing for both hydraulic elements and gear-reducing elements, and is used in some mini-tractors and ride-on lawn mowers.

The 2008-2010 <u>Honda DN-01</u> cruiser motorcycle used a hydrostatic CVT, in the form of a variable displacement axial piston pump with a variable-angle swashplate.

The Japanese Type 10 tank uses hydraulic mechanical transmission.

#### Cone

A cone CVT varies the drive ratio by moving a wheel or belt up and down the axis of conical roller(s). The simplest type of cone CVT, the single-cone version, uses a wheel that moves along the slope of the cone, creating the variation between the narrow and wide diameters of the cone.

Some designs of cone CVTs use two rollers. [19][20] The *Evans Friction Cone*— produced in the 1920s— uses two rollers which are oriented so that a small constant-sized gap is present between the rollers. [21] A leather strap sits in the gap between the rollers, pressed against both rollers in order to transfer motion from the

Evans Friction Cone CVT

input roller to the output roller. The drive ratio of the transmission is adjusted by moving this strap along the axis of the rollers.

In a CVT with oscillating cones, the torque is transmitted via friction from a variable number of cones (according to the torque to be transmitted) to a central, barrel-shaped hub. The side surface of the hub is convex with a specific radius of curvature which is smaller than the concavity radius of the cones. In this way, there will be only one (theoretical) contact point between each cone and the hub at any time.

### Epicyclic

In an epicyclic CVT (also called a *planetary CVT*), the gear ratio is shifted by tilting the axes of spheres in a continuous fashion, to provide different contact radii, which in turn drive input and output discs. The system can have multiple "planets" to transfer torque through multiple fluid patches. Production versions include the *Toyota e-CVT* (which debuted on the 1997 Toyota Prius)<sup>[22]</sup> and the NuVinci CVT.<sup>[23]</sup>

Epicyclic CVT

### Other types

Friction-disk transmissions were used in several tractors and small locomotives built in the early decades of the 20th century. These transmissions consist of an output disk which could be moved across the surface of the input disk upon which it rolled. When the output disk was adjusted to a position equal to its own radius, the resulting drive ratio was 1:1. The drive ratio could be set to infinity (i.e. a stationary output disk) by moving the output disk to the centre of the input disk. The output direction could also be reversed, by moving the disk past the centre of the input disk. The transmission on early <u>Plymouth locomotives</u> worked this way, while on tractors using friction disks, the range of reverse speeds was typically limited.<sup>[24]</sup>

A magnetic CVT transmits torque using a non-contact magnetic coupling rather than physical contact.<sup>[25]</sup> The design uses two rings of permanent magnets with a ring of steel pole pieces between them, in order to create a planetary gearset using magnets.<sup>[26]</sup> It is claimed to produce a 3 to 5 percent reduction in fuel consumption, compared with a mechanical system.<sup>[26]</sup>

### Infinitely variable transmissions

Some CVTs can also function as an *infinitely variable transmission* (IVT) which offer an infinite range of low gears (e.g. moving a vehicle forward at an infinitely slow speed). Some IVTs prevent back-driving (where the output shaft can freely rotate, like an automotive transmission in neutral) due to providing a high back-driving torque. Other IVT, such as ratcheting types, allow the output shaft to freely rotate. The types of CVTs which are able to function as IVTs include epicyclic, friction-disk and ratcheting CVTs.

In an epicyclic CVT, the infinitely low drive ratios are produced when the output shaft rotation speed which is equal to the difference between two other speeds within the CVT. In this situation, the CVT is functioning as a regulator of the rotation speed of any one of the three rotators of the planetary gear system. Since two of the rotators are the input and output of the regulator, the CVT can be configured to result in an output speed of zero for any given input speed. The CVT's input speed is always the same as the motor, even when the output speed is zero.

# Origins

In 1879, <u>Milton Reeves</u> invented a CVT (then called a *variable-speed transmission*) for use in saw milling. In 1879 Reeves began fitting this transmission to his cars, [27] and the Reeves CVT was also used by several other manufacturers.

The 1911 Zenith Gradua 6HP motorcycle used a pulley-based *Gradua* CVT.<sup>[28][29]</sup> A year later, the Rudge-Whitworth Multigear was released with a similar but improved CVT. Other early cars to use a CVT were the 1913-1923 David small three-wheeled cyclecars built in Spain,<sup>[30]</sup> the 1923 Clyno built in the U.K., and the 1926 Constantinesco Saloon built in the U.K.

# Applications

### Automobiles

The first mass-production car to use a CVT was the 1958 <u>DAF 600</u> small sedan built in the Netherlands.<sup>[31]</sup> This <u>Variomatic</u> transmission was used in several vehicles built by DAF and Volvo until the 1980s.<sup>[32]</sup>

The 1987 Ford Fiesta (second generation) and Fiat Uno (first generation) became the first cars to be equipped with steel-belted CVT (as opposed to the less robust rubber-belted DAF design). The <u>Multitronic</u> <u>transmission</u> was developed by Ford, Van Doorne, and Fiat, with work on the transmission starting in 1976.<sup>[33]</sup>

Also in 1987, the *ECVT* was introduced as an optional transmission on the Subaru Justy, [34][35] Production was limited to 500 units per month as Van Doorne's Transmissie in The Netherlands could only produce this many steel belts for them. In June, supplies increased to 3,000 per month, leading Subaru to make the CVT available in the Subaru Rex Kei car. [36] Subaru has also supplied its CVTs to other manufacturers (such as the 1992 Nissan Micra). [33]

The 1996 Honda Civic (sixth generation) introduced a pulley-based *Multi Matic* CVT which included a torque converter, for low-speed "creep" action).<sup>[37]</sup>

Use of CVTs then spread in the following years to models including the 1998 <u>Nissan Cube</u>, 1999 <u>Rover</u> 25 and 1999 <u>Audi A6.<sup>[38]</sup></u> Marketing terms for CVTs include "Lineartronic" (Subaru), "Xtronic" (Jatco, Nissan, Renault), <u>INVECS-III</u> (Mitsubishi), <u>Multitronic</u> (Volkswagen, Audi), "Autotronic" (Mercedes-Benz) and IVT (Hyundai, Kia).

The 1999 <u>Nissan Cedric (Y34)</u> used a toroidal CVT— unlike the pulley-based designs used by other manufacturers— marketed as the *Nissan Extroid* and which incorporated a torque converter. Nissan then switched from toroidal to pulley-based CVTs in 2003.<sup>[39]</sup> The version of the CVT used with a V6 engine in the <u>Nissan Altima</u> is claimed to be capable of transmitting higher torque loads than other belt CVTs.<sup>[40]</sup>

The 2019 Toyota Corolla (E210) is available with a CVT assisted by a physical "launch gear" alongside the CVT pulley. Up to 40 km/h (25 mph), the transmission uses the launch gear, in order to increase acceleration and reduce the stress on the CVT. Above this speed, the transmission switches over to the CVT pulley. [41]

Several hybrid electric vehicles- such as the Toyota Prius, Nissan Altima and Ford Escape Hybrid- use <u>Electric Variable Transmissions</u> (EVTs) to control the contribution of power from the electric motor and the internal combustion engine. Despite the similar name, these are fundamentally different devices from CVTs (which are powered by a single source).

### Racing cars

In the United States, Formula 500 open-wheeler racing cars have used CVTs since the early 1970s. CVTs were prohibited from Formula One in 1994 (along with several other electronic systems and driver aids) due to concerns over escalating research and development costs, and maintaining a specific level of driver involvement with the vehicles.<sup>[42]</sup>

### Small vehicles

Many small vehicles— such as <u>snowmobiles</u>, <u>golf carts</u> and <u>motor scooters</u>— use CVTs, typically the rubber belt or variable pulley variety. CVTs in these vehicles often use a rubber belt design with a non-stretching fixed circumference manufactured using various highly durable and flexible materials, due to the mechanical simplicity and ease of use outweighing their comparative inefficiency. Some motor scooters include a centrifugal clutch, to assist when idling or manually reversing the scooter.[43]

The 1974 <u>Rokon RT340 TCR Automatic</u> off-road motorcycle was fitted with a snowmobile CVT. The first ATV equipped with a CVT was the Polaris Industries *Trail Boss* in 1985.

### Farm and earthmoving equipment

<u>Combine harvesters</u> used variable belt drives as early as the 1950s. Many small <u>tractors</u> and selfpropelled mowers for home and garden use simple rubber belt CVTs. Hydrostatic CVTs are more common on the larger units. In mowing or harvesting operations, the CVT allows the forward speed of the equipment to be adjusted independently of the engine speed; this allows the operator to slow or accelerate as needed to accommodate variations in thickness of the crop.

Small to medium-sized agricultural and <u>earthmoving equipment</u> often uses hydrostatic CVTs. Since the engines in these machines are typically run at constant power output (to provide hydraulic power or to power machinery), losses in mechanical efficiency are offset by enhanced operational efficiency. For example, in earthmoving equipment, the forward-reverse shuttle times are reduced. The speed and power output of the CVT is used to control the travel speed of the equipment and sometimes also to steer the equipment. In the latter case, the required speed differential to steer the equipment can be supplied by independent CVTs, allowing steering to be accomplished without several drawbacks associated with other skid steer methods (such as braking losses or loss of tractive effort).

The 1965 *Wheel Horse 875* and *1075* garden tractors were the first such vehicles to be fitted with a hydrostatic CVT. The design used a variable-displacement swash-plate pump and fixed-displacement gear-type hydraulic motor combined into a single compact package. Reverse ratios were achieved by reversing the flow of the pump through over-centering of the swash plate. Acceleration was limited and smoothed through use of pressure accumulator and relief valves located between the pump and motor, to prevent the sudden changes in speed possible with a direct hydraulic coupling. Subsequent versions included fixed swash plate motors and ball pumps.

The 1996 *Fendt Vario 926* was the first ever heavy-duty tractor to be equipped with a hydrostatic CVT.<sup>[44]</sup> Over 100,000 tractors have been produced with this transmission.<sup>[44]</sup>

### Power generating systems

CVTs have been used in aircraft electrical power generating systems since the 1950s.

CVTs with flywheels are used as a <u>speed governor</u> between an engine (e.g. a wind turbine) and the <u>electric generator</u>. When the engine is producing sufficient power, the generator is connected directly to the CVT which serves to regulate the engine's speed. When the power output is too low, the generator is disconnected and the energy is stored in the flywheel. It is only when the speed of the flywheel is sufficient that the kinetic energy is converted into electricity, intermittently, at the speed required by the generator.

### Other uses

Some <u>drill presses</u> and <u>milling machines</u> contain a simply belt-drive CVT system to control the speed of the chuck. In this system, the effective diameter of the output shaft pulleys are adjustable due to their conical shape. The pulley on the motor is usually fixed in diameter (or sometimes with discreet steps to allow a selection of speed ranges). The operator adjusts the speed of the drill by using a handwheel that controls the width of the gap between the pulley halves. A tensioner pulley is implemented in the belt transmission to take up or release the slack in the belt as the speed is altered.

Winches and hoists are also an application of CVTs, especially for those adapting the transmission ratio to the resistant torque.

Bicycles with CVT gearing have had limited commercial success, with one example providing a range of gearing equivalent to an eight-speed shifter.<sup>[45]</sup> The bicycle short gearing assisted when cycling uphill, however the CVT was noted to significantly increase the weight of the bicycle.<sup>[46]</sup>

### See also

- Constant speed drive
- Friction drive
- List of automobiles with continuously variable transmissions
- Power band

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